

UNITED STATES PATENT APPLICATION**FOR****BOUNDARY SCAN CELL FOR TESTING AC COUPLED LINE USING PHASE
MODULATION TECHNIQUE****INVENTORS:**

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S P E C I F I C A T I O N

TITLE OF INVENTION

BOUNDARY SCAN CELL FOR TESTING AC COUPLED LINE USING PHASE MODULATION TECHNIQUE

FIELD OF THE INVENTION

[0001] The present invention relates to boundary scan testing of interconnections between integrated circuits. More particularly, the present invention relates to AC coupled boundary scan testing.

BACKGROUND OF THE INVENTION

[0002] Electronic systems generally include at least one printed circuit board (PCB) containing one or more integrated circuit (IC) chips or ICs. ICs typically include input/output (I/O) pins which are coupled to various interconnects of the PCB. Testing performance of electronic systems which include PCBs and ICs typically requires testing at multiple levels including at the chip level, at the board level, and at the system level. Testing at the board level includes testing interconnects of the PCB. Testing at the system level requires analysis of interconnections between and among the ICs, the PCBs, and other devices both on and off the PCB.

[0003] To enhance testability at the board level as well as at the system level, a common design practice at the chip level is to incorporate boundary scan test logic into

an IC in accordance with IEEE Standard 1149.1. This standard specifies the function of JTAG logic, which is named for the Joint Test Action Group, for control of boundary scan testing. Two basic elements of an IC are its core logic and its I/O pins. In accordance with IEEE Standard 1149.1, boundary scan cells (BSCs) are inserted between the core logic and the I/O pins of the IC. BSCs may be used to test the integrity of the interconnections between the plurality of ICs.

[0004] Each IC may be controlled by boundary scan logic, in accordance with IEEE Standard 1149.1, to operate either in a system mode or in a JTAG test mode. In the system mode, system data signals relating to core functions of the IC are passed through the I/O pins to and from devices external to the IC. In the JTAG test mode, test data are provided by the boundary scan chain for the purpose of testing interconnections between the IC and devices external to the IC. The boundary scan logic also provides test control signals which include mode signals, shift signals, clock signals, and update signals, among others, each of which is well known. The shift control signal instructions include a bypass instruction, a sample instruction, and a cross test instruction. The cross test instruction controls BSCs to perform a boundary scan test among the various ICs.

[0005] The IC further includes a test data input (TDI) demultiplexer, a test data output (TDO) multiplexer, a bypass register, an instruction register, an identification register, and a test access port (TAP) controller. The TDI demultiplexer includes an input coupled to receive a test data signal from the boundary scan logic which is typically external to the IC. The TDI demultiplexer includes a first output coupled to a TDI input

of a first BSC of the plurality of BSCs in the IC. Each of the BSCs includes a TDI input and a TDO output. Each of BSCs is connected serially from a TDO output to a TDI input to propagate test data signals from one BSC to the next BSC in the chain. The TDI demultiplexer further includes a second output coupled to an input of the core logic, a third output coupled to an input of the bypass register; a fourth output coupled to an input of the instruction register; and a fifth output coupled to an input of the identification register.

[0006] The TDO multiplexer includes an output which is coupled to provide a test data signal to another IC or to the boundary scan logic. The TDO multiplexer further includes: a first input coupled to a TDO output of a last BSC of the plurality of BSCs in the IC, a second input coupled to an output of the core logic; a third input coupled to an output of the bypass register; a fourth input coupled to an output of the instruction register, and a fifth input coupled to an output of the identification register. The identification register includes inputs coupled to outputs of the TAP controller. The TAP controller includes inputs coupled to receive a *TMS* signal, a *TCK* signal, and a *TRST* signal from the boundary scan logic.

[0007] In general, there are three possible I/O structures for an IC including a two-state I/O structure, a three-state I/O structure, and a bi-directional I/O structure. Each of the three I/O structures provides coupling between the core logic and at least one I/O pin. Any or all of the I/O structures may be used in an IC depending on the particular circumstances. The two-state I/O structure includes a two-state output buffer having an

input and an output. The input of the two-state output buffer is coupled to a system data output of the core logic. The output of the two-state output buffer is coupled to an I/O pin. The three-state I/O structure includes a three-state output buffer having an input, an output, and a control input. The input of the three-state output buffer is coupled to a system data output of the core logic. The output of the three-state output buffer is coupled to an I/O pin. The control input of the three-state output buffer is coupled to a three-state system control signal output line of the core logic. The bi-directional I/O structure includes a bi-directional buffer. The bi-directional buffer includes an output buffer element having an input, an output, and a control input and an input buffer element having an input and an output. The control input of the output buffer element is coupled to a bi-directional control signal output line of the core logic. The input of the output buffer element is coupled to a system data output of the core logic. The output of the input buffer element is coupled to a system data received input of the core logic. The output of the output buffer element and the input of the input buffer element are coupled together with an I/O pin.

[0008] According to conventional methods and apparatus for boundary scan testing, the BSCs are inserted into the I/O structures between the buffers and the core logic. For a two-state output structure, a BSC is inserted between the core logic and the input of the two-state output buffer. For a three-state output structure, a BSC is inserted between the system data output of the core logic and the input of the three-state output buffer. Also, a BSC is inserted between the three-state control signal output line of the core logic and the control input of the three-state output buffer. For a bi-directional

output structure, a BSC is inserted between the system control signal output line of the core logic and the bi-directional output buffer. Also, a bi-directional BSC is inserted between the core logic and the bi-directional output buffer.

[0009] Turning first to FIG. 1, a detailed logic block diagram of a prior art BSC 10 is shown. The BSC 10 includes a boundary scan mode multiplexer (mode multiplexer) 12, a shift multiplexer 14, a data shift/capture register 16, and an update data register 18. The mode multiplexer 12 and the shift multiplexer 14 each have a system input (0), an update input (1), an output, and a select line. The data shift/capture register 16 and the update data register 18 each have a data input (D), a clock input (CLK), a normal output (Q), and an inverted output (Q bar or not Q).

[0010] The BSC 10 includes a system data input (SDI) line for receiving system signals including system data signals and system control signals from the system signal output lines, including the system data signal output lines and the system control signal output lines, of the core logic. If the BSC 10 is used for control purposes, the SDI line may receive a system control signal from the core logic. If the BSC 10 is used for output, the SDI line may receive a system data signal from the core logic. If the BSC 10 is used for an input, the SDI line becomes a system data received input (SDRI) line for receiving signals from the I/O pin through an input buffer. The BSC 10 also includes a system data output (SDO) line for transmitting signals through an output buffer to the I/O pin. If the BSC 10 is used for an input, the SDO line becomes a system data received output (SDRO) line for transmitting signals to the core logic. The SDI line and the SDO line

complete the circuit between the core logic and the I/O structure that was bisected by the insertion of the BSC.

[0011] For control of the mode of operation by the boundary scan logic and for various test inputs from the boundary scan logic, the BSC 10 further includes a number of JTAG lines. Part or all of these lines taken collectively are sometimes referred to as forming a JTAG bus. The primary JTAG lines are a TDI line which may receive a *TDI* signal from the boundary scan logic either directly or via another BSC and a TDO line for providing a *TDO* signal to the boundary scan logic either directly or via another BSC. These two lines are common to all types of BSCs as they are used to form the chain of BSCs. The JTAG lines further include a *ShiftDR* signal input line, a *ClockDR* signal input line, an *UpdateDR* signal input line, and a *Mode* signal input line. Each line is coupled to receive the corresponding signal from the boundary scan logic. The various lines and circuit elements are coupled to one another as shown.

[0012] Turning now to FIG. 2, a detailed logic block diagram of a prior art bi-directional BSC 20 is shown. The bi-directional BSC 20 includes a bi-directional system multiplexer 22, a direction control multiplexer 24, a bi-directional shift control multiplexer 26, a bi-directional data shift/capture register 28, and a bi-directional update data register 30. The bi-directional system multiplexer 22, the direction control multiplexer 24, and the bi-directional shift control multiplexer 26 each have a system input (0), an update input (1), an output, and a select line. The bi-directional data shift/capture register 28 and the bi-directional update data register 30 each have a data

input (D), a clock input (CLK), a normal output (Q), and an inverted output (Q bar or not Q).

[0013] Since the bi-directional BSC 20 serves both as an output and an input, it includes an SDI line, an SDO line, an SDRI line, and an SDRO line as described above. Similarly, the bi-directional BSC 20 includes a TDI line, a TDO line, a *ShiftDR* signal input line, a *ClockDR* signal input line, an *UpdateDR* signal input line, and a *Mode* signal input line. In addition, the bi-directional BSC 20 includes a *DIRCTL* signal input line. Each line is coupled to receive the corresponding signal from the boundary scan logic. The various lines and circuit elements are coupled to one another as shown.

[0014] IEEE Standard 1149.1 was first adopted in 1990. It has been widely used and has proved to be very successful. However, IEEE Standard 1149.1 does not address all situations and design practices. One such practice is the inclusion of capacitive coupling in the interconnections between ICs. A capacitor is added either to the connection between the ICs or to one, the other, or both of the I/O pins of the ICs or the PCBs with connectors. The capacitor is designed to reduce noise and block unwanted common mode voltage differences in the interconnection. For discussion, this will be referred to alternatively as either being AC coupled or DC de-coupled.

[0015] Turning now to FIG. 3, a block diagram of ten possible combinations of DC and AC coupled interconnections between two devices is shown. The choice of which of the combinations shown that are actually used depends on the circumstances.

Because of the capacitor, the value of a signal at the receiving end of the interconnection is no longer the same as the value at the driving end. The result is that conventional IEEE Standard 1149.1 testing becomes impractical on AC coupled interconnections. One will note that there are seven possible AC coupled combinations where IEEE Standard 1149.1 will not work as compared to only three DC coupled combinations where IEEE Standard 1149.1 will work. As the quest for higher signal speeds continues in the future, the use of AC coupling will increase. This becomes especially true with the development of optical communication signals. The consequence will be less and less reliance on conventional IEEE Standard 1149.1 testing.

[0016] A need exists for a boundary scan testing mechanism for AC coupled interconnections that builds on the advantages of conventional IEEE Standard 1149.1 testing. Specifically, a need exists for a boundary scan testing means that is capable of detecting defects in AC coupled interconnections. Ideally, such a detection means would be simple and inexpensive. A primary purpose of the present invention is to solve these needs and provide further, related advantages.

TRANSIENT TESTS

BRIEF DESCRIPTION OF THE INVENTION

[0017] An apparatus and a method for testing Alternating Current (AC) coupled interconnects of a circuit using boundary scan methodology are disclosed. A Boundary Scan Cell (BSC) of a transmitting Integrated Circuit (IC) generates an AC signal based on a value of the BSC of the transmitting IC and a reference clock. A Sync Pulse cell at the receiving IC generates a sync pulse signal to the BSC of the receiving IC. The BSC of the receiving IC captures a default phase of the AC signal in relation to the sync pulse signal and also captures a phase of a source of input signal. The BSC of the receiving IC then compares the phase of the input signal with the phase of said AC signal in relation to the phase captured at the sync pulse signal and sends out an output signal based on the comparison.

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TESTING

BRIEF DESCRIPTION OF THE DRAWINGS

[0018] The accompanying drawings, which are incorporated into and constitute a part of this specification, illustrate one or more embodiments of the present invention and, together with the detailed description, serve to explain the principles and implementations of the invention.

[0019] In the drawings:

[0020] FIG. 1 is a logic block diagram of a prior art Boundary Scan Cell (BSC);

[0021] FIG. 2 is a logic block diagram of a prior art bi-directional BSC;

[0022] FIG. 3 is a block diagram of ten possible combinations of DC and AC coupled interconnections between two devices;

[0023] FIG. 4 is a block diagram of seven possible defects in AC coupled interconnections between two devices detectable by the presently claimed invention;

[0024] FIG. 5 is a block diagram of a transmitting Boundary Scan Cell according to a specific embodiment of the present invention;

[0025] FIG. 6 is a block diagram of a receiving Boundary Scan Cell according to a specific embodiment of the present invention;

[0026] FIG. 7 is a flow diagram of a method for enabling a transmitting Boundary Scan Cell to operate with AC signals according to a specific embodiment of the present invention;

[0027] FIG. 8 is a flow diagram of a method for enabling a receiving Boundary Scan Cell to operate with AC signals according to a specific embodiment of the present invention;

[0028] FIG. 9A is a diagram illustrating possible signals transmitted by a transmitting Boundary Scan Cell according to a specific embodiment of the present invention;

[0029] FIG. 9B is a diagram illustrating other possible signals transmitted by a transmitting Boundary Scan Cell according to a specific embodiment of the present invention;

[0030] FIG. 10A is a diagram illustrating possible signals processed by a receiving Boundary Scan Cell and a Sync Pulse Cell according to a specific embodiment of the present invention; and

[0031] FIG. 10B is a diagram illustrating other possible signals processed by a receiving Boundary Scan Cell and a Sync Pulse Cell according to a specific embodiment of the present invention.

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DETAILED DESCRIPTION

[0032] Embodiments of the present invention are described herein in the context of a method and apparatus for testing AC coupled interconnections. Those of ordinary skill in the art will realize that the following detailed description of the present invention is illustrative only and is not intended to be in any way limiting. Other embodiments of the present invention will readily suggest themselves to such skilled persons having the benefit of this disclosure. Reference will now be made in detail to implementations of the present invention as illustrated in the accompanying drawings. The same reference indicators will be used throughout the drawings and the following detailed description to refer to the same or like parts.

[0033] In the interest of clarity, not all of the routine features of the implementations described herein are shown and described. It will, of course, be appreciated that in the development of any such actual implementation, numerous implementation-specific decisions must be made in order to achieve the developer's specific goals, such as compliance with application- and business-related constraints, and that these specific goals will vary from one implementation to another and from one developer to another. Moreover, it will be appreciated that such a development effort might be complex and time-consuming, but would nevertheless be a routine undertaking of engineering for those of ordinary skill in the art having the benefit of this disclosure.

[0034] FIG. 4 is a block diagram illustrating seven possible defects in AC coupled interconnections between two devices detectable by the presently claimed

invention. A first net 402 has a missing capacitor in its circuit. A second net 404 has an opening in its circuit on the driving end. A third net 406 has an opening in its circuit on the receiving end. A fourth net 408 has a driving end stuck at 0. A fifth net 410 has a driving end stuck at 1. A sixth net 412 has a receiving end stuck at 0. A seventh net 414 has a receiving end stuck at 1.

[0035] FIG. 5 is a block diagram illustrating a transmitting boundary scan cell (BSC) according to a specific embodiment of the present invention. The circuit 502 in the box with broken lines represents a transmitter BSC according to a specific embodiment of the present invention. Such transmitter BSC is capable of acting as an ordinary boundary scan cell as well as handling AC signals.

[0036] The transmitter BSC comprises a shift/capture flip-flop 504, an update flip-flop 506, an XOR logic gate 508, and a multiplexor 510. The shift flip-flop 504 is connected to three sources of signals or data input: *bscanShiftIn*, *clockBscanAc*, and *testBscanReset*. The *bscanShiftIn* line allows AC test stimulus (control pattern) to shift in the present BSC. The *clockBscanAc* line is connected to the output of a flip-flop 512 that has two lines of input: *clockBscan* and *refClk*. Flip-flop 512 is generally common to all transmitting BSCs. Shift flip-flop 504 may comprise any generic D-type flip-flop. An output of shift flip-flop 504 is connected to an input of the update flip-flop 506. The output of shift flip-flop 504 is also connected to a *bscanShiftOut* line. The output of a flip-flop 514, having two lines of input: *updateBscan* and *refClk*, is also connected to the input of the update flip-flop 506. The shift flip-flop 504 may comprise any generic D-

type flip-flop. The output of the update flip-flop 506 is connected to an input of the XOR logic gate 508. A *refClk* line is also connected to the input of the XOR logic gate 508. The *refClk* is a clock running at system speed. The output of XOR logic gate 508 is connected to an input of multiplexor 510. The multiplexor 510 is also connected to two lines: *fromCore* and *selectJtagOut*. The output of the multiplexor 510 is connected to a *toPad* line.

[0037] The transmitter BSC generates an AC signal which can pass through a capacitor in an AC coupled net, with attenuation less than 3dB. This transmitter BSC changes the phase of the clock signal by 180 degrees whenever the “Update” cell data changes. With the reset, the update cell needs to have a “0” so that the receiving BSC can sync up.

[0038] The transmitter BSC 502 receives a reference clock signal from the *refClk* line. Based on the value in the update register, the transmitter BSC 502 generates an AC signal that is in phase with the reference clock signal or out of phase by 180 degrees with the reference clock signal. If the transmitter BSC 502 is not in AC JTAG mode, the reference clock signal input to the transmitter BSC 502 is held low thereby allowing the BSC 502 to drive the same DC pattern as is present in the Update register of the transmitter BSC 502.

[0039] In order to set the default phase once in AC JTAG mode, the transmitter BSC needs to be reset through the application of “testBscnReset” line which can be

generated from a conventional Test Access Port (TAP). This ensures that the outgoing phase at test reset corresponds to a “zero” value in the boundary scan register.

[0040] Thus once in AC JTAG mode, continuous AC signals are streaming out of the transmitter BSC 502 and the phase of the AC signals changes whenever the value in the update register changes. If it is a concern for power that these oscillations be turned off except when required (that is between update and capture), this could be accomplished by additional decoding from the TAP. However, this shouldn't be an issue since the systems are designed to work as such under worst case conditions.

[0041] FIG. 6 is a block diagram illustrating a receiving Boundary Scan Cell (BSC) according to a specific embodiment of the present invention. The circuit 602 in the box with broken lines represents a receiving BSC according to a specific embodiment of the present invention. Such receiving BSC is capable of acting as an ordinary boundary scan cell as well as handling AC signals.

[0042] The receiving BSC 602 comprises a sampling flip-flop 604, a first multiplexor 606, a second flip-flop 608, an XOR logic gate 610, a second multiplexor 612, a third multiplexor 614, and a third flip-flop 616. The sampling flip-flop 604 is connected to two sources of input: a *fromPad* line and the *refClk* line. The sampling flip-flop 604 may comprise any generic D-type flip-flop. An output of the sampling flip-flop 604 is connected to an input of the first multiplexor 606. A *syncPulse* line connected a Sync Pulse cell 618 connects to select input of the first multiplexor 606. An output of the

first multiplexor 606 connects to an input of the second flip-flop 608. Another input of the second flip-flop 608 is connected to the *refClk* line. An output of the second flip-flop 608 is connected to an input of the XOR logic gate 610. Another output of the second flip-flop 608 is feedback to another input of the first multiplexor 606. The output of the sampling flip-flop 604 is also connected to another input of the XOR logic gate 610. An output of the XOR logic gate 610 is connected to an input of the second multiplexor 612. The output of the sampling flip-flop 604 is also connected to another input of the second multiplexor 612. An *acjtagMode* line is connected to another input of the second multiplexor 612. An output of the second multiplexor 612 is connected to an input of the third multiplexor 614. The third multiplexor 614 has another input connected to two lines: *bscanShiftIn* and *shiftBscan2Edge*. An output of the third multiplexor 614 is connected to an input of the third flip-flop 616. Another input of the third flip-flop 616 is also connected to a *clockBscan* line. An output of the third flip-flop 616 is connected to a *bscanShiftOut* line.

[0043] The receiving BSC 602 decodes the phase of the AC signal received from the transmitting BSC 502. The receiving BSC 602 decodes the initial phase value and stores it. The initial decode value can be either “0” or “1”. If it is a “1”, the later decodes are inverted. Otherwise, the signals are passed as they are. The initial phase is assumed to be “0”. The input of the receiving BSC 602 is sampled using D-type sampling flip-flops such as the sampling flip-flop 604, with the same clock frequency as the one generated by the transmitting BSC 502. The output of the sampling flip-flop 604 toggles whenever the phase of the input changes.

[0044] The receiving BSC 602 is based on capturing the phase of the transmitting BSC 502. That is, in order to recognize phase changes, the receiving BSC 602 has to capture the default phase (i.e. the phase when AC JTAG mode is entered and the transmitting BSC contains a zero in its Update Register). This is accomplished by generating an internal sync pulse, which is common in all receiving BSCs. The internal sync pulse is generated when the receiving BSC 602 enters the AC JTAG mode. In order to switch to AC JTAG mode, all integrated circuits under test must be in AC JTAG mode during the same instruction cycle. The sync pulse switches the “defaultPhase” flop 608 to the sampling flops’ output and thus captures the default phase. Since the sync pulse is not generated again until the test is exited, this default phase remains captured.

[0045] If a “zero” is loaded, the phase corresponds to the default phase. Such default phase causes the other input of the XOR logic gate 610 to be the same as the defaultPhase resulting in a “zero” being propagated out to the capture flop 616. In a capture state while in AC JTAG mode, the capture flop 616 will capture a “zero.”

[0046] If a “one” is loaded at the transmitting cell, the phase inverts from the default and the change in phase is captured by the sampling flop 604 and fed as the input to the XOR logic gate 610. The XOR logic gate 610 then changes the phase to a “one” as its default input is the inverse of the input from the sampling flop 604. Thus, the “one” updating at the transmitting BSC 502 is captured at the receiving BSC 602.

[0047] If the receiving BSC 602 needs to be in a non AC JTAG mode, it will sample the output of the pin directly instead of sampling the XOR logic gate 610 output. Thus, the legacy operation of boundary scan is duplicated.

[0048] FIG. 7 is a flow diagram illustrating a method for enabling a transmitting Boundary Scan Cell (BSC) to operate with AC signals according to a specific embodiment of the present invention. In a first block 702, the transmitting BSC 502 detects whether it is functioning in AC JTAG mode. If the transmitting BSC 502 is not in AC JTAG mode, the reference clock input line *refclk* is held low in a block 704, thereby allowing the BSC to drive the same DC pattern as is present in the update register of the transmitting BSC. In block 706, if the transmitting BSC 502 is in AC JTAG mode, the transmitting BSC 502 is reset as described above. In block 708, the transmitting BSC generates AC signal based on the value of the transmitting BSC and the active reference clock as described above. The AC signal is then sent out to the receiving BSC 602 in block 710. Examples of AC signals produced by the transmitting BSC 602 are illustrated in FIG. 9A and 9B.

[0049] FIG. 8 is a flow diagram illustrating a method for enabling a receiving Boundary Scan Cell (BSC) to operate with AC signals according to a specific embodiment of the present invention. In a first block 802, the receiving BSC 602 detects whether it is functioning in AC JTAG mode. If the receiving BSC 602 is not in AC JTAG mode, the receiving BSC 602 functions as a conventional Boundary Scan Cell in a conventional 1149.1 testing in block 804. The receiving BSC 602 is capable of working

like an ordinary receiving BSC or an AC JTAG cell. The principle in detecting the phase of the AC signals received is to sample it with a D-type flop-flop, such as the sampling flip-flop 604, using the clock of the same frequency and meeting the setup and hold time. Thus the output of the sampling flip-flop 604 changes where there is a change in phase of the incoming signal. This change is illustrated in FIG. 10A and FIG. 10B.

[0050] If the receiving BSC 502 is in AC JTAG mode, a Sync Pulse by the Sync Pulse Cell 618, as described above, is generated in block 806. In the AC JTAG mode, the receiving BSC 602 detects the default phase and makes the “phaseDecode” as “0”. The Sync Pulse cell 618 generates a “sync_pulse” signal of 1refClk period, once we enter Ac jtag mode reset, with “selectJtagOutput” and “AcjtagMode” going high. “SelectJtagOutput” is delayed sufficiently to allow the transmitting BSC to send the AC signal so that the receiver can capture it. “SelectJtagOutput” is the mode signal defined in the standard test 1149.1, which gives the pin permission in EXTEST instruction. In block 808, with this “SyncPulse,” the default phase is captured and stored at “defaultPhase” signal. The flip-flop 604 driving the “phase” signal has the clock and input of the same frequency so that it captures either a one or a zero depending on the phase. In block 810, the incoming signal is also captured using the same process.

[0051] In block 812, the incoming signal and the stored signal are compared. If a “zero” is loaded at the transmitting cell, the phase corresponds to the default phase in block 814. Such default phase causes the other input of the XOR logic gate 610 to be the same as the defaultPhase resulting in a “zero” being propagated out to the capture flop

616. In a capture state while in AC JTAG mode, the capture flop 616 will capture a "zero" in block 816.

[0052] If a "one" is loaded in block 818, the phase inverts from the default and the change in phase is captured by the sampling flop 604 and fed as the input to the XOR logic gate 610. The XOR logic gate 610 then changes the phase to a "one" as its default input is the inverse of the input from the sampling flop 604. Thus, the "one" updating at the transmitting BSC 502 is captured at the receiving BSC 602 in block 816.

[0053] It should be noted that the AC signal or pattern from the transmitter BSC 502 is based on the reference clock signal fed to the transmitter BSC 502. This reference clock signal can be derived from the clock tree that would feed a source synchronous clock, which would be the sampling clock in the receiving BSC 602, and thus maintaining a definite phase relationship between the transmitted pattern and the clock sampling. This relationship is necessary just as in case of a function data signal for the scheme to work. Thus in other clocking schemes, the constant phase between transmitted and sampling clock should be maintained.

[0054] The advantages of the presently claimed invention are numerous. First, the reference clock on the board can be used. This reference clock signal goes to the integrated circuits, which have this interface. If the reference clock signal has more than 3dB attenuation, then this clock needs to be multiplied and used in the integrated circuit. Second, there is no need for any synchronization mechanism between the transmitting

BSC and the receiving BSC. And last, the reference clock is connected to the integrated circuits with this interface so that controls of skew are very easy. Thus, the BSCs as described above work as either ordinary IEEE 1149.1 or as AC JTAG cells.

[0055] While embodiments and applications of this invention have been shown and described, it would be apparent to those skilled in the art having the benefit of this disclosure that many more modifications than mentioned above are possible without departing from the inventive concepts herein. The invention, therefore, is not to be restricted except in the spirit of the appended claims.

PROOF-OF-SEQUENCE